

Ordinary differential Equations

UNIT-I: Linear Equation with constant coefficients

Second order homogeneous Equations - Initial value problems - linear dependence and independence - Wronskian and formula for wronskian - Non homogeneous equations of order two

Chapter 2: Sec 1 to 6

UNIT-II: Continue

Homogeneous and Non-homogeneous equation of order n - Initial value problem - Annihilator method to solve non homogeneous equation - Algebra of constant coefficient operators.

Chapter 3: Sec 4 to 12

UNIT-III: Linear Equations with variable coefficient

Initial value problem - Existence and uniqueness theorem - Solution to solve a non homogeneous equations - Wronskian and linear independence - Reduction of the a homogeneous equation - homogeneous equation with analytic coefficients - The Legendre's equation

Chapter 3: Sec 1 to 8

UNIT-IV: Linear Equations with regular singular points

UNIT - I

①

Linear Equation with constant coefficient

Section - 1

Introduction:

A linear differential equation of order n with constant coefficient is of the form

$$a_0 y^n + a_1 y^{n-1} + a_2 y^{n-2} + \dots + a_n y = b(x) \rightarrow ①$$

where $a_0 \neq 0$, a_1, a_2, \dots, a_n are complex constant and

b is some complex value function on the interval I

$$a_0 = 1, \text{ we get}$$

$$y^n + a_1 y^{n-1} + a_2 y^{n-2} + \dots + a_n y = b(x) \rightarrow ②$$

$$\text{Take } L(y) = y^n + a_1 y^{n-1} + \dots + a_n y \rightarrow ③$$

$$② \Rightarrow L(y) = b(x) \rightarrow ④$$

If $b(x) = 0 \quad \forall x \in I$ equation ④ become

$L(y) = 0$ and is called homogenous equation.

If $b(x) \neq 0$ equation ④ is called non-homogenous

equation.

Note: L is called differential operator. If $\varphi(x)$ is a function with derivatives upto order n then

$$L[\varphi(x)] = \varphi^n(x) + a_1 \varphi^{n-1}(x) + \dots + a_n \varphi(x)$$

$$L[\varphi] = \varphi^n + a_1 \varphi^{n-1} + \dots + a_n \varphi$$

When ever $L[\varphi(x)] = b(x)$ then $\varphi(x)$ is called

solt of the equation

$$L(y) = b(x)$$

Section - 2

The second order homogenous equation:

Here we are considered the equation

$$L(y) = y'' + a_1 y' + a_2 y = 0 \rightarrow \textcircled{1}$$

where a_1 and a_2 are constants, we recall that the 1st order equation with constant coefficient $y' + a_1 y = 0$ has a soln $e^{-a_1 x}$ the constant a_1 is this soln is the soln of the equation

$$y' + a_1 y = 0$$

for some appropriate constant y , e^{yx} will be a soln of the equation $\textcircled{1}$

$$L(e^{yx}) = [y^2 + a_1 y + a_2] e^{yx}$$

and e^{yx} will be a soln of $L(y) = 0$

i) $L(e^{yx}) = 0$ if y satisfies

$$y^2 + a_1 y + a_2 = 0$$

We let

$$p(r) = r^2 + a_1 r + a_2$$

and call $p(r)$ the characteristic polynomial

$$\text{ii) } L(e^{yx}) = p(r) e^{yx} \quad \forall r \text{ and } x.$$

Theorem: 1

Let a_1, a_2 be a constant and consider the equation
 $L(y) = y'' + a_1 y' + a_2 y$.

- (i) If r_1, r_2 are two distinct roots of the characteristic polynomial $p(r)$ then the function q_1 and q_2 are defined by $q_1(x) = e^{r_1 x}$ and $q_2(x) = e^{r_2 x}$.

Proof:

Consider the equation

$$(i) \quad L(y) = y'' + a_1 y' + a_0 y = 0 \rightarrow ①$$

characteristic polynomial is

$$P(x) = x^2 + a_1 x + a_0 = 0$$

Since γ_1, γ_2 are roots of $P(x)$ then

$$P(\gamma_1) = 0, \quad P(\gamma_2) = 0$$

$$P(\gamma_1) = \gamma_1^2 + a_1 \gamma_1 + a_0 = 0 \quad \} \rightarrow ②$$

$$P(\gamma_2) = \gamma_2^2 + a_1 \gamma_2 + a_0 = 0 \quad \}$$

$$L[\Phi_1(x)] = L[e^{\gamma_1 x}]$$

$$= (e^{\gamma_1 x})'' + a_1 (e^{\gamma_1 x})' + a_0 e^{\gamma_1 x}$$

$$= \gamma_1^2 (e^{\gamma_1 x}) + a_1 \gamma_1 (e^{\gamma_1 x}) + a_0 e^{\gamma_1 x}$$

$$= e^{\gamma_1 x} [\gamma_1^2 + a_1 \gamma_1 + a_0]$$

$$= e^{\gamma_1 x} (0)$$

$$L[\Phi_1(x)] = 0$$

$$L[\Phi_2(x)] = L[e^{\gamma_2 x}]$$

$$= (e^{\gamma_2 x})'' + a_1 (e^{\gamma_2 x})' + a_0 e^{\gamma_2 x}$$

$$= \gamma_2^2 (e^{\gamma_2 x}) + a_1 \gamma_2 (e^{\gamma_2 x}) + a_0 e^{\gamma_2 x}$$

$$= e^{\gamma_2 x} [\gamma_2^2 + a_1 \gamma_2 + a_0]$$

$$= e^{\gamma_2 x} (0)$$

$$L[\Phi_2(x)] = 0$$

$\therefore \Phi_2(x)$ soln of $L(y) = 0$.

(ii) When $\gamma_1 = \gamma_2$

$$P(x) = \gamma_1^2 + a_1 \gamma_1 + a_0 = 0 \rightarrow ③$$

$$P'(x) = 2\gamma_1 a_1 = 0$$

$$\Phi(x) = x e^{\gamma_1 x}$$

$$L[\Phi(x)] = L[x e^{\gamma_1 x}]$$

$$= (x e^{\gamma_1 x})'' + a_1 (x e^{\gamma_1 x})' + a_0 (x e^{\gamma_1 x})$$

$$= (x \gamma_1^2 e^{\gamma_1 x} + 2\gamma_1 x e^{\gamma_1 x})' + a_1 2\gamma_1 x e^{\gamma_1 x} + a_0 x e^{\gamma_1 x} + a_0 x^2 e^{\gamma_1 x}$$

$$\begin{aligned}
 &= x e^{r_1 x} r_1^2 + r_1 e^{r_1 x} + r_1 e^{r_1 x} + a_1 x r_1 e^{r_1 x} + a_1 e^{r_1 x} + a_2 x e^{r_1 x} \\
 &= x e^{r_1 x} [r_1^2 + a_1 r_1 + a_2] + [2r_1 + a_1] e^{r_1 x} \\
 &= x e^{r_1 x} (0) + (0) e^{r_1 x} \\
 &= 0
 \end{aligned}$$

$\therefore L[\varphi_1(x)]$ is the soln of $L(y)=0$

$\varphi_2(x) = x e^{r_1 x}$ is the soln of $L[\varphi(x)]$

Note:

Let $\varphi_1(x), \varphi_2(x)$ be soln of $L(y)=0$ then

$\varphi = c_1 \varphi_1 + c_2 \varphi_2$ is also soln of $L(y)=0$.

Proof:

Since φ_1, φ_2 are soln

$$L[y] = y'' + a_1 y' + a_2 y = 0$$

$$L[\varphi_1] = \varphi_1'' + a_1 \varphi_1' + a_2 \varphi_1 = 0$$

$$L[\varphi_2] = \varphi_2'' + a_1 \varphi_2' + a_2 \varphi_2 = 0$$

$$L[\varphi] = L[c_1 \varphi_1 + c_2 \varphi_2]$$

$$= (c_1 \varphi_1 + c_2 \varphi_2)'' + a_1(c_1 \varphi_1 + c_2 \varphi_2)' + a_2(c_1 \varphi_1 + c_2 \varphi_2)$$

$$= c_1 \varphi_1'' + c_2 \varphi_2'' + a_1 c_1 \varphi_1' + a_2 c_2 \varphi_2' + a_2 c_1 \varphi_1 + a_2 c_2 \varphi_2$$

$$= (\varphi_1'' + a_1 \varphi_1' + a_2 \varphi_1) c_1 + (\varphi_2'' + a_1 \varphi_2' + a_2 \varphi_2) c_2$$

$$= (0) c_1 + (0) c_2$$

$$L[\varphi] = 0$$

\therefore Hence $\varphi = c_1 \varphi_1 + c_2 \varphi_2$ is the soln of $L(y)=0$.

Section-3

Initial value problems for second order equations

Consider the equation

$$L(y) = y'' + a_1 y' + a_2 y = 0 \rightarrow \textcircled{1}$$

An initial value problem for $\textcircled{1}$ is the problem of finding a soln y satisfying

$$y(x_0) = \alpha, \quad y'(x_0) = \beta \rightarrow \textcircled{2}$$

where x_0 some real number α and β are two given constant

\therefore The above initial value problem

$$L(y) = 0$$

$$y(x_0) = \alpha$$

$$y'(x_0) = \beta$$

Theorem: 2 (Existence Theorem)

For any real x_0 and constant α, β there exists a soln y of the initial value problem $L(y) = 0$

$$y(x_0) = \alpha, \quad y'(x_0) = \beta \text{ on } -\infty < x < \infty$$

Proof:

Given x_0 is real, α, β are constant interval is

$-\infty < x < \infty$, There are unique constant c_1, c_2 soln

$$q = c_1 q_1 + c_2 q_2 \rightarrow \textcircled{1}$$

The soln of initial value problem

$$q(x_0) = \alpha \} \rightarrow \textcircled{2}$$

$$q'(x_0) = \beta$$

where the soln is q_1 and q_2 are given by

$$q_1, q_2$$

$$q_1(x) = e^{r_1 x} \} \rightarrow \textcircled{3}$$

$$q_2(x) = e^{r_2 x}$$

$$r_1 = r_2$$

$$q_1(x) = e^{r_1 x}$$

$$q_2(x) = x e^{r_1 x}$$

$$\begin{aligned} c_1\varphi_1(x_0) + c_2\varphi_2(x_0) &= d \\ c_1\varphi'_1(x_0) + c_2\varphi'_2(x_0) &= \beta \end{aligned} \quad \rightarrow (5)$$

equation (5) will have a unique soln c_1, c_2
if the determinant

$$\Delta = \begin{vmatrix} \varphi_1 & \varphi_2 \\ \varphi'_1 & \varphi'_2 \end{vmatrix} = \varphi_1\varphi'_2 - \varphi_2\varphi'_1 \neq 0$$

case (i)

If $x_1 \neq x_2$

$$\begin{aligned} \varphi_1(x) &= e^{x_1 x}, \quad \varphi'_1(x) = x_1 e^{x_1 x} \\ \varphi_2(x) &= x_2 e^{x_2 x}, \quad \varphi'_2(x) = x_2 e^{x_2 x} \end{aligned}$$

$$\begin{aligned} \text{Now } \Delta &= \varphi_1\varphi'_2 - \varphi'_1\varphi_2 \\ &= e^{x_1 x} x_2 e^{x_2 x} - x_1 e^{x_1 x} e^{x_2 x} \\ &= e^{x_1 x} e^{x_2 x} (x_2 - x_1) \\ &= \frac{(x_1 + x_2)x}{(x_2 - x_1)} \neq 0 \\ \Delta &= (x_2 - x_1) e^{\frac{(x_1 + x_2)x}{(x_2 - x_1)}} \neq 0 \end{aligned}$$

$\therefore \Delta \neq 0$

case (ii)

$$\begin{aligned} \text{If } x_1 &= x_2 \\ \varphi_1(x) &= e^{x_1 x}, \quad \varphi'_1(x) = x_1 e^{x_1 x} \\ \varphi_2(x) &= x_2 e^{x_1 x}, \quad \varphi'_2(x) = x_2 x_1 e^{x_1 x} + e^{x_1 x} \end{aligned}$$

$$\begin{aligned} \text{Now, } \Delta &= \varphi_1\varphi'_2 - \varphi'_1\varphi_2 \\ &= e^{x_1 x} (x_2 x_1 e^{x_1 x} + e^{x_1 x}) - x_1 e^{x_1 x} x_2 e^{x_1 x} \\ &= x_2 x_1 e^{2x_1 x} + e^{2x_1 x} - x_2 x_1 e^{2x_1 x} \\ &= e^{2x_1 x} \neq 0 \end{aligned}$$

$\Delta \neq 0$

Therefore the determinate condition is satisfied in either case, thus if c_1, c_2 are the unique constants satisfying the function

$$\varphi = c_1\varphi_1 + c_2\varphi_2$$

Defn:

Let $\varphi(x)$ be any soln of $L(y)=0$ then the magnitude (size) of $\varphi(x)$ is defined as

$$\|\varphi(x)\| = \sqrt{\|\varphi(x)\|^2 + \|\varphi'(x)\|^2}$$

$$\Rightarrow \|\varphi(x)\|^2 = \|\varphi(x)\|^2 + \|\varphi'(x)\|^2$$

also size of φ will be measured by

$$K = 1 + |\alpha_1| + |\alpha_2|$$

Result:

If b and c any two constants

$$|b| |c| \leq b^2 + c^2$$

$$0 \leq (b - c)^2$$

$$\leq b^2 + c^2 - 2|b||c|$$

Theorem: 3

Let φ be any solution of $L(y) = y'' + \alpha_1 y' + \alpha_2 y = 0$ on an interval I containing a point x_0 then for x in I

$$\|\varphi(x)\| e^{-K|x-x_0|} \leq \|\varphi(x)\| \leq \|\varphi(x_0)\| e^{K|x-x_0|}$$

where

$$\|\varphi(x)\|^2 = \|\varphi(x)\|^2 + \|\varphi'(x)\|^2 \text{ and } K = 1 + |\alpha_1| + |\alpha_2|$$

Proof:

Given equation

$$L(y) = y'' + \alpha_1 y' + \alpha_2 y = 0 \rightarrow ①$$

and φ is a soln of ①

$$\text{let } u(x) = \|\varphi(x)\|^2$$

$$u(x) = \|\varphi(x)\|^2 + \|\varphi'(x)\|^2$$

$$u = \|\varphi\|^2 + \|\varphi'\|^2$$

$$u = \varphi \bar{\varphi} + \varphi' \bar{\varphi}'$$

Differentiate u w.r.t x

$$u' = \varphi \bar{\varphi}' + \varphi \bar{\varphi}' + \varphi' \bar{\varphi}' + \varphi' \bar{\varphi}''$$

$$|u'| \leq |\varphi'| |\bar{\varphi}| + |\varphi| |\bar{\varphi}'| + |\varphi'| |\bar{\varphi}'| + |\varphi| |\bar{\varphi}''|$$

$$\leq |\varphi'| |\varphi| + |\varphi| |\varphi'| + |\varphi''| |\varphi| + |\varphi| |\varphi''|$$

$$\leq 2|\varphi| |\varphi'| + 2|\varphi| |\varphi''| \rightarrow ②$$

since φ satisfies equation ① we have

(8)

$$\varphi'' = 0$$

$$\varphi'' + a_1\varphi' + a_2\varphi = 0$$

$$\varphi'' = -a_1\varphi' - a_2\varphi$$

$$\Rightarrow |\varphi''| \leq |a_1||\varphi'| + |a_2||\varphi| \rightarrow ③$$

sub ③ in ④ we get

$$|u'| \leq 2|\varphi||\varphi'| + 2|\varphi'||(a_1||\varphi'| + a_2||\varphi|)$$

$$\leq 2|\varphi||\varphi'| + 2|a_1||\varphi'|^2 + 2|\varphi||\varphi'||a_2|$$

$$|u'| \leq (1+|a_2|)|\varphi||\varphi'| + 2|a_1||\varphi'|^2 \rightarrow ④$$

W.L.G.T

$$2|b||c| \leq |b|^2 + |c|^2 \rightarrow ⑤$$

using ⑤ in ④

$$|u'| \leq (1+|a_2|)[|\varphi|^2 + |\varphi'|^2] + 2|a_1||\varphi'|^2$$

$$\leq (1+|a_2|)|\varphi|^2 + (1+|a_2|)|\varphi'|^2 + 2|a_1||\varphi'|^2$$

$$\leq (1+|a_2|)|\varphi|^2 + (1+2|a_1|+|a_2|)|\varphi'|^2 \rightarrow ⑥$$

this inequality

$$\Rightarrow e^{-2ku} (u - 2ku) \leq 0$$

$$(e^{-2ku} u)' \leq 0$$

If $x \geq x_0$ we integrate this equation with respect x ,

$x_0 \rightarrow x$

$$\int_{x_0}^x (e^{-2ku} u)' \leq 0$$

$$[e^{-2ku} u]_{x_0}^x \leq 0$$

$$e^{-2kx} u(x) - e^{-2kx_0} u(x_0) \leq 0$$

$$e^{-2kx} u(x) \leq e^{-2kx_0} u(x_0)$$

$$u(x) \leq e^{\frac{2k(x-x_0)}{-2k}} u(x_0)$$

$$\Rightarrow \|u(x)\|^2 \leq e^{2k(x-x_0)} \|u(x_0)\|^2$$

$$\Rightarrow \|u(x)\| \leq e^{\frac{k(x-x_0)}{2}} \|u(x_0)\| \rightarrow \textcircled{1}$$

Similarly consider the left inequality of left

limit $x < x_0$

$$\lim_{x \rightarrow x_0^-} \frac{u(x)}{e^{-k(x-x_0)}} \leq \|u(x)\| \rightarrow \textcircled{2}$$

Combine $\textcircled{1}$ and $\textcircled{2}$

$$\|u(x_0)\| e^{-\frac{k(x-x_0)}{2}} \leq \|u(x)\| \leq \|u(x_0)\| e^{\frac{k(x-x_0)}{2}}$$

Theorem 4 (Uniqueness Theorem)

Let a, b are any two constant and let x_0 be any

real number on any interval I containing x_0 atmost one

solv y of the I.V.P $y'(y)=0$, $y(x_0)=a$, $y'(x_0)=b$

Proof:

Let φ and ψ , we two soln of the given problem

$$\text{let } \theta = \varphi - \psi \rightarrow \textcircled{1}$$

$$\text{then } L(\theta) = L(\varphi) - L(\psi)$$

$$= 0 - 0$$

$$L(\theta) = 0$$

by ①

$$\theta(x_0) = \varphi(x_0) - \psi(x_0)$$

$$= \alpha - \alpha$$

$$\theta(x_0) = 0$$

Similarly $\theta'(x_0) = \varphi'(x_0) - \psi'(x_0)$

$$= \beta - \beta$$

$$\theta'(x_0) = 0$$

$$\|\theta(x_0)\|^2 = |\theta(x_0)|^2 + |\theta'(x_0)|^2$$

$$= 0 + 0$$

$$\|\theta(x_0)\|^2 = 0$$

using the inequality of previous theorem

$$\|\varphi(x_0)\| e^{-k|x-x_0|} \leq \|\varphi(x)\| \leq \|\varphi(x_0)\| e^{k|x-x_0|} \rightarrow ②$$

from the function of θ

$$\|\theta(x_0)\| = 0 \quad \forall x \text{ in } I$$

$$\Rightarrow \theta(x_0) = 0 \quad \forall x \text{ in } I$$

$$\Rightarrow \varphi = \psi$$

Hence atmost one soln. φ of the initial value problem

$$\varphi(x_0) = \alpha, \quad \varphi'(x_0) = \beta, \quad L(\varphi) = 0$$

Theorem: 5

Let φ_1, φ_2 be two soln of $L(y) = 0$ given by

$\varphi_1(x) = e^{\gamma_1 x}, \quad \varphi_2(x) = e^{\gamma_2 x}$ in case $\gamma_1 \neq \gamma_2$ (distinct) and

$\varphi_1(x) = c_1 e^{\gamma x}, \quad \varphi_2(x) = c_2 e^{\gamma x}$ in case $\gamma_1 = \gamma_2$ (repeated). If c_1, c_2 are any two constants then

function $\varphi = c_1 \varphi_1 + c_2 \varphi_2$ is a soln of $L(y) = 0$ on $-\infty < x < \infty$.

conversely if φ is any soln of $L(y) = 0$ on $-\infty < x < \infty$

there are unique constant c_1, c_2 such that $\varphi = c_1 \varphi_1 + c_2 \varphi_2$.

Proof:

First Part

Let φ_1, φ_2 be two solns of $L(y) = 0$ that is

$$\varphi_1(x) = e^{\gamma_1 x}, \quad \varphi_2(x) = e^{\gamma_2 x}$$

24 - 26.9.79

Assume that among 2dn of $L(u)$, on which there are unique constant signs such that $\alpha_1, \alpha_2, \dots, \alpha_n$ are the signs of $L(u)$.
Now prove that $Q = C_1\alpha_1 + C_2\alpha_2 + \dots + C_n\alpha_n$ is a solution of $L(u) = 0$.
 $L(u) = L(C_1\alpha_1 + C_2\alpha_2 + \dots + C_n\alpha_n) = 0$
 $L(u) = C_1L(\alpha_1) + C_2L(\alpha_2) + \dots + C_nL(\alpha_n)$
 $L(u) = (C_1\alpha_1 + C_2\alpha_2 + \dots + C_n\alpha_n)(C_1\alpha_1 + C_2\alpha_2 + \dots + C_n\alpha_n)$
 $L(u) = C_1^2\alpha_1^2 + C_2^2\alpha_2^2 + \dots + C_n^2\alpha_n^2 + 2C_1C_2\alpha_1\alpha_2 + 2C_1C_3\alpha_1\alpha_3 + \dots + 2C_1C_n\alpha_1\alpha_n + 2C_2C_3\alpha_2\alpha_3 + \dots + 2C_2C_n\alpha_2\alpha_n + 2C_3C_4\alpha_3\alpha_4 + \dots + 2C_{n-1}C_n\alpha_{n-1}\alpha_n + 2C_nC_1\alpha_n\alpha_1 + 2C_nC_2\alpha_n\alpha_2 + 2C_nC_3\alpha_n\alpha_3 + \dots + 2C_nC_{n-1}\alpha_n\alpha_{n-1}$
 $L(u) = C_1L(\alpha_1) + C_2L(\alpha_2) + \dots + C_nL(\alpha_n)$
 $L(u) = 0$

$\therefore Q$ is the soln of $L(u) = 0$
i.e. Q is a solution of $L(u) = 0$ and hence
if we take $\alpha_1, \alpha_2, \dots, \alpha_n$ such that
 \Rightarrow there exist constant signs $\alpha_1, \alpha_2, \dots, \alpha_n$ satisfying
 $Q = C_1\alpha_1 + C_2\alpha_2 + \dots + C_n\alpha_n$ then Q is a solution of $L(u) = 0$
i.e. Q is a solution of $L(u) = 0$ and its antiderivative
converges pointwise.

Let Q be the soln of $L(u) = 0$ i.e. $Q'(x_0) = \beta$ and
by existence theorem there exists a solution of $L(u) = 0$ in a neighborhood of x_0 .
 $L(u) = 0$,
 $Q(x_0) = d$
 $Q'(x_0) = \beta$ such that
 $Q = C_1\alpha_1 + C_2\alpha_2 + \dots + C_n\alpha_n$
where C_1, C_2, \dots, C_n are unique constants determined by d, β
by uniqueness theorem from $Q(x_0) = d$ and $Q'(x_0) = \beta$
 $Q = \Psi$
Hence the theorem.

Section - 4

Linear dependent and independent

Defn: Linearly dependent

Two functions φ_1, φ_2 on an interval I are said to be linearly dependent on I if \exists two constants not both zero such that

$$c_1\varphi_1(x) + c_2\varphi_2(x) = 0 \quad \forall x \in I$$

Defn: Linearly Independent

The functions φ_1 and φ_2 are said to be linearly independent on I . If the constant c_1 and c_2 are such that

$$c_1\varphi_1(x) + c_2\varphi_2(x) = 0 \quad \forall x \in I$$

$$\Rightarrow c_1 = c_2 = 0$$

(or)

Two functions φ_1 and φ_2 are said to be linearly independent on I . If there not linearly dependent on I .

Wronskian of two functions:

Wronskian of two functions φ_1 and φ_2 defined on I is denotes $w(\varphi_1, \varphi_2)$ is given as

$$w(\varphi_1, \varphi_2) = \begin{vmatrix} \varphi_1 & \varphi_2 \\ \varphi_1' & \varphi_2' \end{vmatrix}$$

$$= \varphi_1\varphi_2' - \varphi_2\varphi_1'$$

Example:

$$\text{Let } \varphi_1(x) = \sin x, \quad \varphi_2(x) = \cos x$$

$$\varphi_1'(x) = \cos x, \quad \varphi_2'(x) = -\sin x$$

$$w(\varphi_1, \varphi_2)(x) = \begin{vmatrix} \sin x & \cos x \\ \cos x & -\sin x \end{vmatrix}$$

$$= -\sin^2 x - \cos^2 x$$

$$= -(\sin^2 x + \cos^2 x)$$

$$w(\varphi_1, \varphi_2)(x) = -1$$

Theorem: 6

Two solns q_1, q_2 of $L(y) = 0$ are linearly independent on interval I , iff $w(q_1, q_2)(x) \neq 0$ $\forall x$ in I .

Proof:

Let us suppose $w(q_1, q_2)(x) \neq 0 \forall x \in I$ and

let c_1, c_2 be constants \exists

$$c_1 q_1(x) + c_2 q_2(x) = 0 \rightarrow \textcircled{1} \quad \forall x \in I$$

also by differential \textcircled{1} w.r.t x

$$c_1 q_1'(x) + c_2 q_2'(x) = 0 \rightarrow \textcircled{2} \quad \forall x \in I$$

for a fixed x , the equation \textcircled{1} and \textcircled{2} are linearly homogeneous equations satisfied by c_1, c_2

the determinant of the coefficient is $w(q_1, q_2)(x)$ which is not zero.

$\therefore c_1 = 0, c_2 = 0$ is only soln of \textcircled{1} and \textcircled{2}

$\therefore q_1, q_2$ are linearly independent on I .

conversely

let us assume q_1, q_2 are linearly independent on I

T.P: $w(q_1, q_2)(x) \neq 0 \forall x \in I$

there exists $w(q_1, q_2)(x_0) = 0$

take the equations

$$c_1 q_1(x_0) + c_2 q_2(x_0) = 0$$

$$c_1 q_1'(x_0) + c_2 q_2'(x_0) = 0$$

where c_1 and c_2 are constant

These are linearly homogeneous equations.

Here the determinant of the constant

$$\text{i.e. } w(q_1, q_2)(x_0) = 0$$

\therefore at least one of the constants c_1, c_2 is not zero.

For the constants c_1, c_2 we have

$$c_1 q_1(x) + c_2 q_2(x) = 0 \quad \forall x \in I$$

case when c_1, c_2 is not zero.

Let c_1, c_2 such a soln consider the function

$$\psi = c_1 \varphi_1 + c_2 \varphi_2$$

Now, $L(\psi) = 0$

$$\psi(x_0) = 0, \quad \psi'(x_0) = 0$$

$\Rightarrow \varphi_1, \varphi_2$ are linearly independent on I .

The contradicts the statement of the theorem.

$$w(\varphi_1, \varphi_2)(x) \neq 0 \quad \forall x \in I$$

Hence the theorem.

Theorem 7:

Let φ_1, φ_2 two solns of $L(y) = 0$ on an interval I

and let x_0 be any point in I Then φ_1, φ_2 are linearly independent on I iff $w(\varphi_1, \varphi_2)(x_0) \neq 0$

linearly independent on I iff $w(\varphi_1, \varphi_2)(x_0) \neq 0$

Proof:

Let φ_1, φ_2 be linearly independent on I

by above theorem

$$w(\varphi_1, \varphi_2)(x) \neq 0 \quad \forall x \in I$$

In particular

$$w(\varphi_1, \varphi_2)(x_0) \neq 0$$

conversely

$$\text{let } w(\varphi_1, \varphi_2)(x_0) \neq 0$$

claim:

φ_1, φ_2 are linearly independent on I .

consider the equations

$$c_1 \varphi_1(x_0) + c_2 \varphi_2(x_0) = 0$$

$$c_1 \varphi_1'(x_0) + c_2 \varphi_2'(x_0) = 0 \quad \forall x_0 \in I$$

where c_1, c_2 are constants.

Since the determinant of above linearly homogeneous equation is

$$w(\varphi_1, \varphi_2)(x_0) = \begin{vmatrix} \varphi_1(x_0) & \varphi_2(x_0) \\ \varphi_1'(x_0) & \varphi_2'(x_0) \end{vmatrix} = \varphi_1(x_0)\varphi_2'(x_0) - \varphi_2(x_0)\varphi_1'(x_0)$$

we obtained $c_1 \varphi_1(x) + c_2 \varphi_2(x) = 0 \quad \forall x \in I$

$$\text{and } c_1 = c_2 = 0$$

thus φ_1, φ_2 are linearly independent on I .

Theorem: 8

Let φ_1, φ_2 be any two L.I. soln of $L(y)=0$ on an interval I . Then every soln φ of $L(y)=0$ can be written uniquely as $\varphi = c_1\varphi_1 + c_2\varphi_2$ where c_1, c_2 are constant.

Proof:

Let x_0 be a point in I .

Given that φ_1, φ_2 are L.I. on I

A.K.T

$$w(\varphi_1, \varphi_2)(x_0) \neq 0$$

Let φ be any soln with $\varphi(x_0) = \alpha, \varphi'(x_0) = \beta$

Consider two equations

$$c_1\varphi_1(x_0) + c_2\varphi_2(x_0) = \alpha = \varphi(x_0) \rightarrow \textcircled{1}$$

$$c_1\varphi'_1(x_0) + c_2\varphi'_2(x_0) = \beta = \varphi'(x_0) \rightarrow \textcircled{2}$$

where c_1, c_2 are constants satisfying \textcircled{1} and \textcircled{2}

Let c_1, c_2 be these constants then the functions

$\psi = c_1\varphi_1 + c_2\varphi_2$ is such that

$$\psi(x_0) = c_1\varphi_1(x_0) + c_2\varphi_2(x_0)$$

$$= \alpha$$

$$\psi'(x_0) = \varphi(x_0)$$

$$\psi'(x_0) = c_1\varphi'_1(x_0) + c_2\varphi'_2(x_0)$$

$$= \beta$$

$$\psi'(x_0) = \varphi'(x_0)$$

$$L(\psi) = L(c_1\varphi_1 + c_2\varphi_2) = 0 \quad (\text{as } \varphi_1, \varphi_2 \text{ are L.I.})$$

$$\psi = \varphi$$

$\therefore \psi$ is a soln & φ is $L(y)=0$

uniqueness theorem

$$\varphi = c_1\varphi_1 + c_2\varphi_2$$

Hence proved.

Section-5

A formula for the Wronskian

Theorem: 9

If q_1, q_2 are two solns of $L(y)=0$ on interval I containing at point x_0 then

$$w(q_1, q_2)(x) = e^{-\int_{x_0}^x a_1(x-t) dt} w(q_1, q_2)(x_0)$$

Proof:

since q_1, q_2 are two soln of

$$L(y) = y'' + a_1 y' + a_2 y = 0 \rightarrow \text{①}$$

We have

$$L(q_1) = q_1'' + a_1 q_1' + a_2 q_1 = 0 \rightarrow \text{②}$$

$$L(q_2) = q_2'' + a_1 q_2' + a_2 q_2 = 0 \rightarrow \text{③}$$

$$\text{②} \times q_2 \Rightarrow q_2 q_1'' + a_1 q_1' q_2 + a_2 q_1 q_2 = 0$$

$$\text{③} \times q_1 \Rightarrow q_1 q_2'' + a_1 q_2' q_1 + a_2 q_1 q_2 = 0$$

$$(q_1 q_2'' - q_2 q_1'') + a_1 (q_1 q_2' - q_2 q_1') = 0 \rightarrow \text{④}$$

If $w = w(q_1, q_2)$

$$= \begin{vmatrix} q_1 & q_2 \\ q_1' & q_2' \end{vmatrix}$$

$$w = q_1 q_2' - q_1' q_2 \rightarrow \text{⑤}$$

$$w' = q_1 q_2'' + q_1' q_2' - q_1' q_2' - q_2 q_1'' = (q_1 q_2' - q_2 q_1'')$$

$$w' = q_1 q_2'' - q_2 q_1'' \rightarrow \text{⑥}$$

sub ④ and ⑤ in ⑥

$$w' + a_1 w = 0$$

$$\frac{dw}{dx} + a_1 w = 0$$

$$\frac{dw}{dx} = -a_1 w$$

$$\frac{dw}{w} = -a_1 dx$$

$$\int \frac{dw}{w} = -a_1 \int dx$$

$$\log w = -a_1 x + \log c$$

$$\log w - \log c = -a_1 x$$

$$\log(\frac{w}{c}) = -a_1 x$$

$$w/c = e^{-a_1 x}$$

$$w = c e^{-a_1 x} \rightarrow \textcircled{1}$$

Put $x = x_0$

$$w(x_0) = c e^{-a_1 x_0}$$

$$c = w(x_0) e^{a_1 x_0} \rightarrow \textcircled{2}$$

Sub \textcircled{2} in \textcircled{1}

$$w = w(x_0) e^{\frac{a_1 x_0 - a_1 x}{e^{a_1 x}}}$$

$$w = w(x_0) e^{\frac{-a_1(x-x_0)}{e^{a_1 x}}}$$

$$\Rightarrow w(Q_1, Q_2)(x) = e^{\frac{-a_1(x-x_0)}{e^{a_1 x}}} w(Q_1, Q_2)(x_0)$$

Section - 6

The Non-homogeneous equations of order two

Theorem: 10

Let 'b' be continuous on an interval I. Every

Soln of $L(y) = b(x)$ on I can be written as

$y = y_p + c_1 q_1 + c_2 q_2$ where y_p is a particular soln

q_1, q_2 are two L.I. Soln of $L(y) = 0$ and c_1, c_2 are

constants. A particular soln y_p

i) Given that $y_p(x) = \int_{x_0}^x \frac{q_1(t) q_2(x) - q_1(x) q_2(t)}{w(Q_1, Q_2)(t)} b(t) dt$

conversely every such y_p is a soln of $L(y) = b(x)$.

Proof:

Let us consider the homogenous equation

$$L(y) = y'' + a_1 y' + a_0 y = 0 \rightarrow \textcircled{1}$$

Given Q_1, Q_2 are two linear independent of $L(y) = 0$

ii) Soln is $c_1 q_1 + c_2 q_2 \rightarrow \textcircled{2}$

where c_1, c_2 are constants

Let us choose

$$\psi_p(x) = u_1(x)\varphi_1(x) + u_2(x)\varphi_2(x) \rightarrow \textcircled{3}$$

be a particular soln of

$$L(y) = b(x) \rightarrow \textcircled{4}$$

$$L(\psi_p) = b(x)$$

$$(i) L(\psi_p) = \psi_p'' + a_1\psi_p' + a_2\psi_p = b(x) \rightarrow \textcircled{5}$$

$$\psi_p = u_1\varphi_1 + u_2\varphi_2$$

$$\psi_p' = u_1\varphi_1' + u_1'\varphi_1 + u_2\varphi_2' + u_2'\varphi_2 \rightarrow \textcircled{6}$$

$$\begin{aligned} \psi_p'' &= u_1\varphi_1'' + \varphi_1'u_1 + u_1'\varphi_1' + u_1''\varphi_1 + u_2\varphi_2'' + u_2'\varphi_2' + u_2''\varphi_2 \\ &\quad + u_2''\varphi_2 \end{aligned}$$

$$\psi_p'' = u_1\varphi_1'' + 2u_1'\varphi_1' + 2u_2'\varphi_2' + u_1''\varphi_1 + u_2\varphi_2'' + u_2''\varphi_2 \rightarrow \textcircled{7}$$

Sub \textcircled{3}, \textcircled{6}, \textcircled{7} in \textcircled{5}

$$\begin{aligned} (u_1\varphi_1'' + 2u_1'\varphi_1' + 2u_2'\varphi_2' + u_1''\varphi_1 + u_2\varphi_2'' + u_2''\varphi_2) + \{ &= b(x) \\ a_1[u_1\varphi_1' + u_1'\varphi_1 + u_2\varphi_2' + u_2'\varphi_2] + & \\ a_2[u_1\varphi_1 + u_2\varphi_2] & \end{aligned}$$

$$\begin{aligned} a_1[\varphi_1'' + a_1\varphi_1' + a_2\varphi_1] + u_2[\varphi_2'' + a_1\varphi_1' + a_2\varphi_2] - \{ &= b(x) \\ + 2[u_1\varphi_1' + u_2\varphi_2'] + [u_1''\varphi_1 + u_2''\varphi_2] + & \\ a_1[u_1\varphi_1 + u_2\varphi_2] & \end{aligned}$$

$$\begin{aligned} 2[u_1\varphi_1' + u_2\varphi_2'] + [u_1''\varphi_1 + u_2''\varphi_2] + \{ &= b \rightarrow (*) \\ a_1[u_1\varphi_1 + u_2\varphi_2] & \end{aligned}$$

assume

$$u_1\varphi_1 + u_2\varphi_2 = 0 \rightarrow \textcircled{8}$$

$$[u_1\varphi_1 + u_2\varphi_2]' = 0 \rightarrow \textcircled{9}$$

$$u_1''\varphi_1 + u_1'\varphi_1' + u_2''\varphi_2 + u_2'\varphi_2' = 0$$

$$(u_1''\varphi_1 + u_2''\varphi_2) + (u_1'\varphi_1' + u_2'\varphi_2') = 0 \rightarrow \textcircled{10}$$

Sub \textcircled{8}, \textcircled{9}, \textcircled{10} in $(*)$

$$u_1\varphi_1 + u_2\varphi_2 = b \rightarrow \textcircled{11}$$

equation ⑧ and ⑪ are two linear equations for u_1, u_2 with the determinant which is $w(\varphi_1, \varphi_2)$. This w is never zero on I. Because φ_1, φ_2 are linearly independent.

∴ There exists unique soln of u_1, u_2

$$w(\varphi_1, \varphi_2) = \begin{vmatrix} \varphi_1 & \varphi_2 \\ \varphi_1' & \varphi_2' \end{vmatrix}$$

$$= \varphi_1 \varphi_2' - \varphi_1' \varphi_2 \rightarrow ⑫$$

$$⑧ \times \varphi_1' \Rightarrow u_1 \varphi_1' \varphi_1 + u_2' \varphi_1' \varphi_2 = 0$$

$$⑪ \times \varphi_1 \Rightarrow \underbrace{u_1 \varphi_1' \varphi_1 + u_2' \varphi_1' \varphi_2}_{u_2' (\varphi_1' \varphi_2 - \varphi_1 \varphi_2')} = b \varphi_1$$

$$u_2' (\varphi_1' \varphi_2 - \varphi_1 \varphi_2') = -b \varphi_1$$

$$-u_2' (\varphi_1 \varphi_2' - \varphi_1' \varphi_2) = -b \varphi_1$$

$$u_2' = \frac{b \varphi_1}{(\varphi_1 \varphi_2' - \varphi_1' \varphi_2)}$$

$$u_2' = \frac{b \varphi_1}{w(\varphi_1, \varphi_2)}$$

Similarly

$$u_1' = -\frac{\varphi_2 b}{w(\varphi_1, \varphi_2)}$$

If x_0 is in I, we get

$$u_1 = - \int_{x_0}^x \frac{\varphi_2(t) b(t)}{w(\varphi_1, \varphi_2)(t)} dt$$

$$u_2' = \int_{x_0}^x \frac{\varphi_1(t) b(t)}{w(\varphi_1, \varphi_2)(t)} dt$$

The soln $y_p = u_1 \varphi_1 + u_2 \varphi_2$ then takes the form

$$y_p(x) = \int_{x_0}^x \left[\frac{\varphi_1(t) \varphi_2(x) - \varphi_2(t) \varphi_1(x)}{w(\varphi_1, \varphi_2)(t)} \right] b(t) dt$$

converse part

$$L[y] = y'' + a_1 y' + a_2 y = b(x)$$